

# Photointerrupter, double-layer mold type

## RPI-303

The RPI-303 is standard tall package photointerrupter. This product can be fix on PCB by snap.

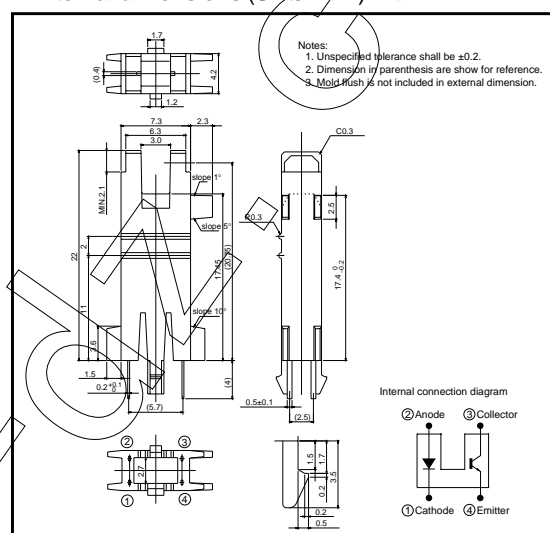
### ●Application

Reel count sensor for VCR

### ●Features

- 1) Tall package (Optical axis 20.75mm)
- 2) Small package due to the double-layer mold
- 3) PPS package for heat resistance

### ●External dimensions (Units: mm)



### ●Absolute maximum ratings (Ta = 25°C)

Parameter		Symbol	Limits	Unit
Input(LED)	Forward current	$I_F$	50	mA
	Reverse voltage	$V_R$	5	V
	Power dissipation	$P_D$	80	mW
Output (photo-transistor)	Collector-emitter voltage	$V_{CEO}$	30	V
	Emitter-collector voltage	$V_{ECO}$	4.5	V
	Collector current	$I_C$	30	mA
	Collector power dissipation	$P_C$	80	mW
Operating temperature		$T_{opr}$	-25~+85	°C
Storage temperature		$T_{stg}$	-30~+85	°C

## Sensors

## ●Electrical and optical characteristics (Ta = 25°C)

	Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions
Input characteristics	Forward voltage	$V_F$	—	1.3	1.6	V	$I_F=50\text{mA}$
	Reverse current	$I_R$	—	—	10	$\mu\text{A}$	$V_R=5\text{V}$
Output characteristics	Dark current	$I_{CEO}$	—	—	0.5	$\mu\text{A}$	$V_{CE}=10\text{V}$
	Peak sensitivity wavelength	$\lambda_P$	—	800	—	nm	—
Transfer characteristics	Collector current	$I_C$	0.2	0.7	2.0	mA	$V_{CE}=5\text{V}$ , $I_F=20\text{mA}$
	Collector-emitter saturation voltage	$V_{CE(sat)}$	—	—	0.4	V	$I_F=20\text{mA}$ , $I_C=0.1\text{mA}$
	Response time	$t_r \cdot t_f$	—	10	—	$\mu\text{s}$	$V_{CC}=5\text{V}$ , $I_F=20\text{mA}$ , $R_L=100\Omega$

## ●Electrical and optical characteristic curves

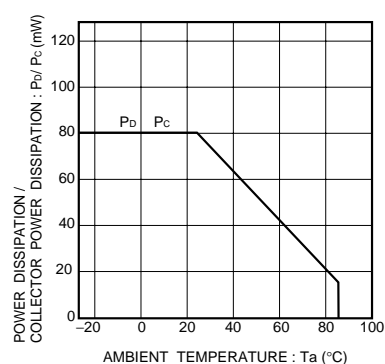


Fig.1 Power dissipation / collector power dissipation vs. ambient temperature

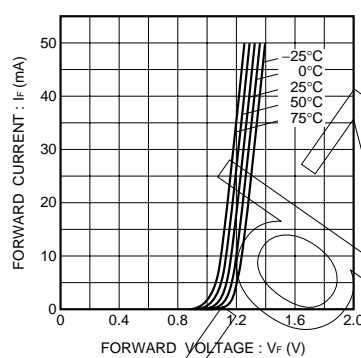


Fig.2 Forward current vs. forward voltage

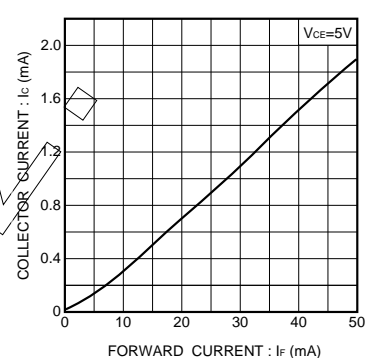


Fig.3 Collector current vs. forward current

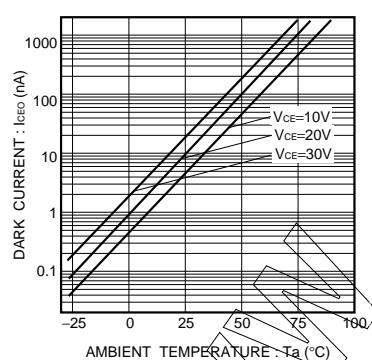


Fig.4 Dark current vs. ambient temperature

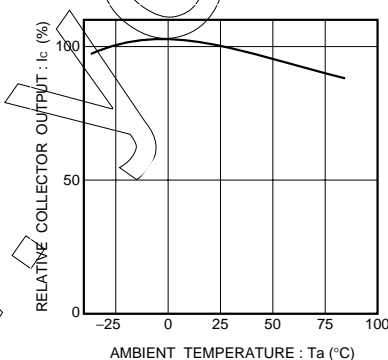


Fig.5 Relative output vs. ambient temperature

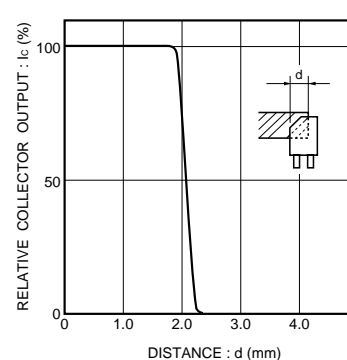
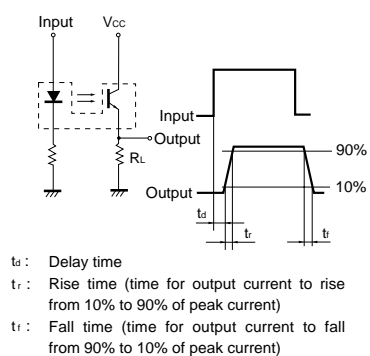
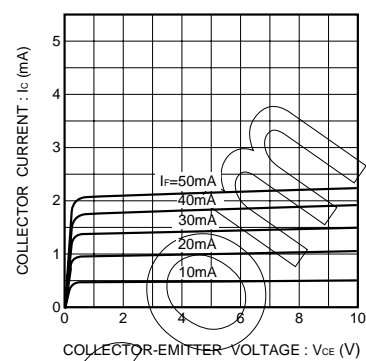
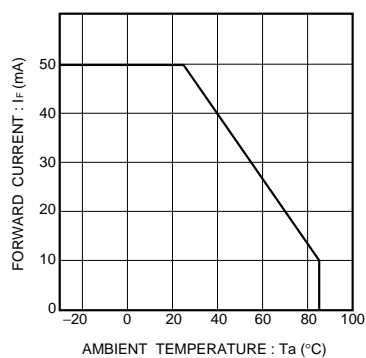
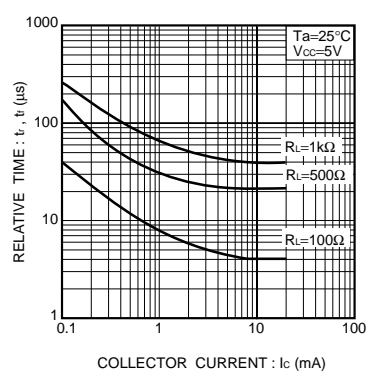


Fig.6 Relative output vs. distance

## Sensors



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