

What is passive infrared type? This sensor detects changes in infrared radiation which occur when there is movement by a person (or object) which is different in temperature from the surroundings. ① As this sensor detects temperature differences, it is well suited to detecting the motion of people by their body temperature. ② Wide sensing area. Sensor Temperature difference Infrared radiation Movement

FEATURES

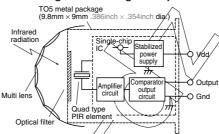
1. The world's smallest with a built-in amplifier

Extremely compact. Ideal for use in miniaturized devices.

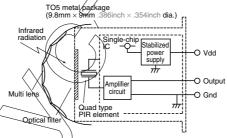
2. Dual lens colors (white and black) are provided

With an ultrasmall design and dual lens colors (white and black), it is inconspicuous, allowing the user to select either white or black to match the equipment color. This provides greater flexibility in equipment design.

- Both digital output and analog output (with adjustable sensitivity) are available.
- **4. Built-in amplifier for easy use** Has a built-in amplifier, and can be connected directly to a microcomputer.
- · Block diagram of the digital output circuit



Block diagram of the analog output circuit



5. Detects even slight motion of a person

With our sensor, even slight motions made by people will be detected easily.

• Fine motion detection capability within approximately 2 meters of sensor.

Standard type:

Detects movement of approximately 30cm 11.811inch.

Slight motion detection type:

Detects movement of approximately 20cm 7(874 bch.

- 6. Noise withstanding capability
 Circuitry is contained in a TO5 metal package, providing at least twice the noise withstanding capability as conventional type.
- Comparison example of noise withstanding capability

	Distance at which motion sensor is not affected by cellular phone noise
Conventional type	Min. 1 to 2m 3.281 to 6.562ft
MP Motion Sensor	Min. 1 to 2cm .394 to .787inch

7. A low current consumption type (46 AA) has also been added to the line-up.

A type that keeps current consumption to $46 \,\mu\text{A}$ (less than 30% compared to predecessor) is now available. Ideal for battery driven devices.

*Digital output type only.

APPLICATIONS

1. Home appliances

Useful for saving energy in air conditioner, television, personal computer, or ventilator and air purifier

2. Amusement machine market Useful for saving energy and for automated guidance in theme parks and large video

games

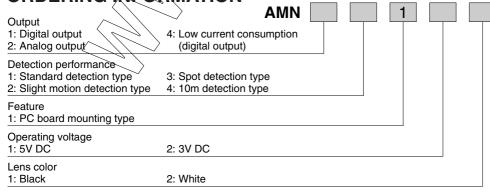
3. Equipment in service market
Useful for automated guidance, automated

announcements and energy saving in vending

machines, ATMs, etc. 4. Lighting market

Automated on/off controls, etc. for lamps, desk lamps, indoor lights, halls, stairway lights, etc.

ORDERING INFORMATION



PRODUCT TYPES

1. Digital output

Rated operating	Detection performance		Ambient temperature	Lens color	Part No.	Packing quantity	
voltage	Detection pen	Fait No.			Inner	Outer	
		Standard	-	Black	AMN11111	50 pcs. 1,	1,000 pcs.
	Standard detection type			White	AMN11112		
	Standard detection type	Low current consumption		Black	AMN41121		
				White	AMN41122		
		Standard	-20 to +60°C -4 to +140°F	Black	AMN12111		
	Slight motion detection type			White	AMN12112		
		Low current consumption		Black	AMN42121		
3 to 6 V DC				White	AMN42122 🔇		
3100 1 00	Spot detection type	Standard		Black	AMN13111		
				White	AMN13/12		
		Low current		Black	AMN43121		
		consumption		White	AMN43√22		
		Standard		Black	AMN14111		
	10m detection type			White	/AMN14112		
		Low current		Black	(AMN44121)		
		consumption		White	AMN44122		

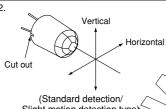
2. Analog output

Rated operating voltage	Detection performance	Ambient temperature	Lens color	Part No.	Packing quantity	
nated operating voltage	Detection performance	Ambient temperature	Lens color	raitino.	Inner	Outer
4.5 to 5.5 V DC	Standard detection type		Black	AMN21111		1,000 pcs.
		-20 to +60°C -4 to +140°F	/White	AMN21112		
	Slight motion		✓Black /	AMN22111		
	detection type		White Black	AMN22112	50 pcs.	
	Spot detection type			AMN23111		
			White	AMN23112		
	10m detection type		Black	AMN24111		
	10m detection type		White	AMN24112		

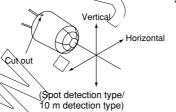
PERFORMANCE

1. Detection performance

Items		Standard detection type	Slight motion detection type	Spot detection type	10m detection type	Conditions of objects to be detected
Rated detection distance*Remark 1		5m 16.404ft (Max.)	2m 6.562ft (Max.)	5m 16.404ft (Max.)	10m 32.808ft (Max.)	Detectable difference in temperature between the target and background for the spot type is more than 4°C 39.2°F. Movement speed Standard detection type/Spot detection type/
Datastian	Horizontal*Remark 2	100°	91°	38°	110°	10m detection type: 0.5 to 1.5 m/s • Slight motion detection type: 0.3 to 1.0 m/s
	Vertical*Remark 2	82°	91° _	\\ 22°	93°	3. Detection object = human body (size is 700mm × 250mm 27.559inch × 9.843inch, but for the slight motion detection
	Detection zone*Remark 3	64 zones	104 zones	24 zones	80 zones	type the size is 200mm × 200mm 7.874inch × 7.874inch)
*B						



(Standard detection/ Slight motion detection type)



*Remarks 1. Depending on the difference in temperature between the background and detection target and the speed at which the target moves, these sensors may be capable of detection beyond the detection distances stated above. Nevertheless, they should be used within the prescribed detection distances. For further details, refer to the detection range diagram on page 14.

3. Regarding of detection zone, please refer to "DETECTION PERFORMANCE" on page 14.

2. Rating (Measuring condition: ambient temp. = 25°C 77°F) (Common to All types)

Items	Specified value	Remarks
Power supply voltage	-0.3 to 7 V DC	
Usable ambient temperature	−20 to 60°C −4 to +140°F	No freezing and condensing at low temperature.
Storage temperature	−20 to 70°C −4 to +158°F	
	<u> </u>	

3. Electrical characteristics (Measuring condition: ambient temp. = 25°C 77°F; operating voltage = 5V) (Common to All types)

1) Digital output

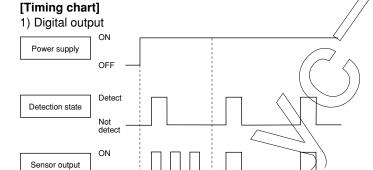
Items		Symbol	Specifie	Measured		
		Syllibol	Standard type	Low current consumption type	conditions	
		Minimum		3.0 V DC	2.2 V DC	
Reted operating vol	tage	Typical	Vdd	_	_	
	Ma			6.0 V DC	3.0 V DC	
		Typical	lw	170 μΑ	46 μ A	lout = 0
(Standby) *Remark		Maximum	100	300 μΑ	60 μΑ	iout – o
Outout	Current	Maximum	lout	100 μA	100 μΑ	Vout ≧ Vdd–0.5
Output (when detecting)	Voltage	Minimum	Vout	Vdd -0.5	Vdd -0.5	Open when not
(which detecting)	voltage	Maximum Maximum		_	/	detecting
Circuit stability time Typical Maximum			Twu	7 s	7 \$	
		Maximum		30 s	30 s	

Remark: The current which is consumed during detection consists of the standby consumed current plus the output current

2) Analog output

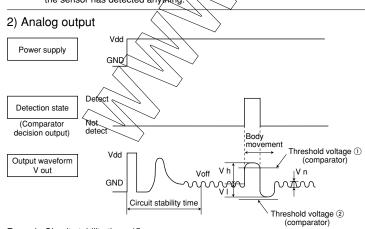
-) /a.og output						
Items		Symbol	Specified value	Measured conditions		
Reted operating voltage	Minimum Maximum	Vdd	4.5 V DC 5.5 V DC			
Reted consumption current	Typical Maximum	lw	0.17 mA 0.3 mA	lout = 0		
Output current	Maximum	lout	50 μA			
Output voltage	Minimum Typical Maximum	Vout	0 V 2.5 V Vdd			
Output offset average voltage	Minimum Typical Maximum	Voff	2.3 V 2.5 V 2.7 V	Steady-state output voltage when not detecting		
Steady-state noise	Typical Maximum	Vn	130 m Vp-p 300 m Vp-p			
Circuit stability time	Maximum	Twu	√ 45 s			

Note: To set to the same detection performance as the digital type, set the output voltage to the effect voltage (2.5V) ±0.45V (i.e. 2.95V or more and 2.05V or less).



Circuit stability time

Remark: Circuit stability time: 30s max.
While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.



Remark: Circuit stability time: 45s max.

While the circuitry is stabilizing after the power is turned on, the sensor output is not fixed in the "on" state or "off" state. This is true regardless of whether or not the sensor has detected anything.

DETECTION PERFORMANCE

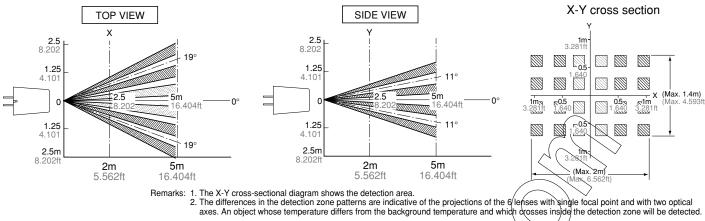
1. Standard detection type

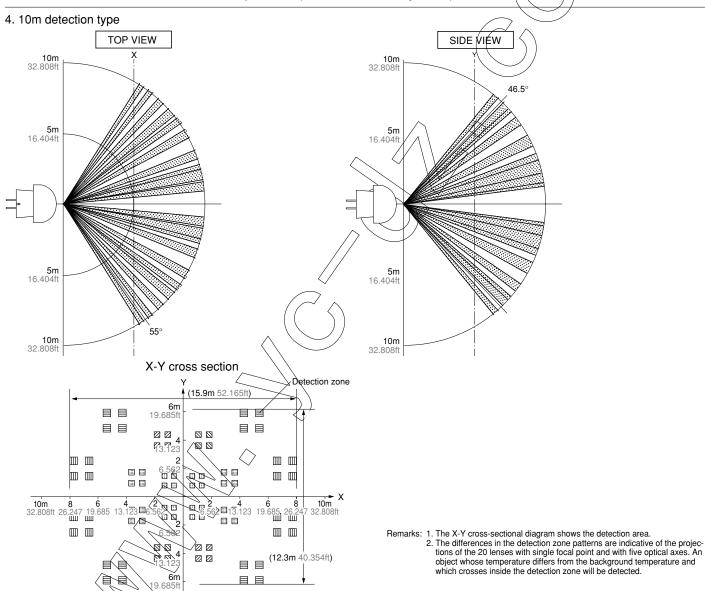


Remarks: 1. The X-Y cross-sectional diagram shows the detection area.

2. The differences in the detection zone patterns are indicative of the projections of the 26 lenses with single focal point and with three optical axes. An object whose temperature differs from the background temperature and which crosses inside the detection zone will be detected.

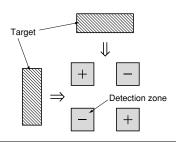
3. Spot detection type





5. Notes regarding the detection zone

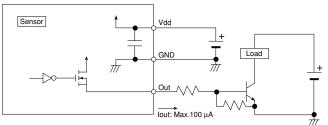
The detection zone has the polarity shown in the diagram on the right. When targets enter both the + and - zones with the same timing, the signals are cancelled each other, thus in this case there is a possibility that the object cannot be detected at the maximum specified detection distance.



HOW TO USE

1. Wiring diagram

1) Digital output

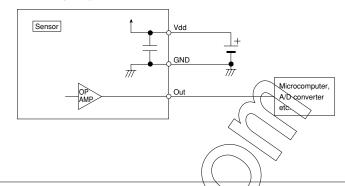


Vdd: Input power source (DC)

GND: GND

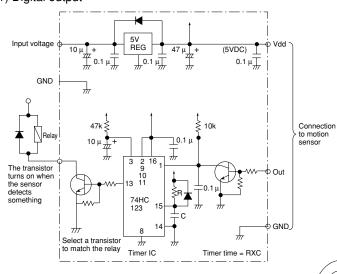
Out: Output (Comparator)

2) Analog output



2. Timer circuit example

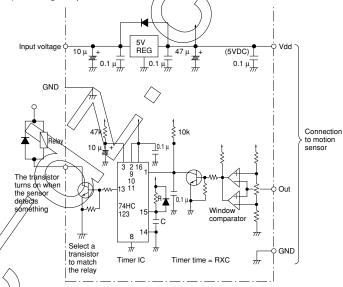
1) Digital output



Note: This is the reference circuit which drives the MP motion sensor. Install noise filter for applications requiring enhanced detection reliability and noise withstanding capability.

Differences in the specifications of electronic components to which the units are connected sometimes affect their correct operation; please check the units' performance and reliability for each application.

2) Analog output



Note: This circuit is a sample of a drive circuit for the MP Motion Sensor. Its noise resistance and long-term reliability are not considered or investigated.

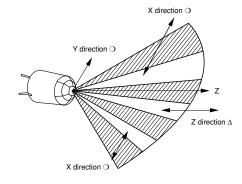
To improve the detection reliability and noise resistance of the circuit, consider adding a noise filter.

Matsushita Electric Works, Ltd. accepts no responsibility for damages resulting from the use of this circuit.

3. Installation

Install the sensor so that people will be entering from the X or Y direction shown below. If persons approach the sensor from the ${\bf Z}$ direction,

detection distance will be shortened.



mm inch General tolerance $\pm 0.5 \pm .020$

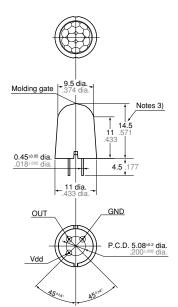
DIMENSIONS

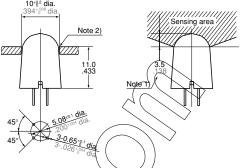
1. Standard detection type

Recommended PC board pattern (BOTTOM VIEW)







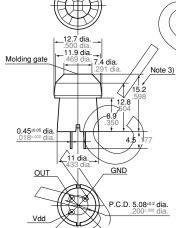


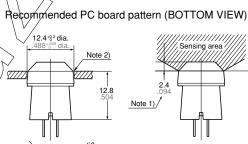
- Notes: 1. In order to ensure proper detection, install it with the lens exposed at least 3.5mm .138inch.
 - 2. As for panel mounting hole, tapering or making a large size hole should be done.
 - The height dimension does not include the remaining molding gate.

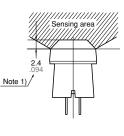
2. Slight motion detection type



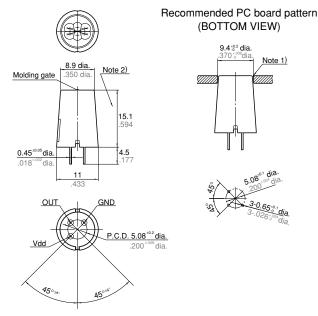








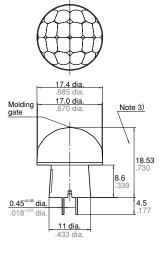
3. Spot detection type

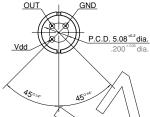


Notes: 1. As for panel mounting hole, tapering or making a large size hole should be

2. The height dimension does not include the remaining molding gate.

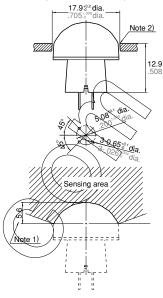
4. 10m detection type





mm inch General tolerance ±0.5 ±.020

Recommended PC board pattern (BOTTOM VIEW)



- 1. In order to ensure proper detection, install it with the lens
- exposed at least 5.6mm .220inch.

 As for panel mounting hole, tapering or making a large size hole should be done.
- The height dimension does not include the remaining mold

NOTES

1. Checkpoints relating to principle of operation

MP motion sensors are passive infrared sensors which detect changes in the infrared rays. They may fail to detect successfully if a heat source other than a human being is detected or if there are no temperature changes in or movement of a heat source. Care must generally be taken in the following cases. The performance and reliability of the sensors must be checked out under conditions of actual use.

<1> Cases where a heat source other than a human being is detected.

- 1) When a small animal enters the detec-
- When the sensor is directly exposed to sunlight, a vehicle's headlights, and incandescent light or some other source of far infrared rays.
- 3) When the temperature inside the detection range has changed suddenly due to the entry of cold or warm air from an air-conditioning or heating unit, water vapor from a humidifier, etc.

<2> Cases where it is difficult to detect the heat source

1) When an object made of glass, acrylic or other subject which far infrared rays have difficulty passing through is located between the sensor and what is to be detected.

2) When the heat source inside the detection range hardly moves or when it moves at high speed; for details on the movement speed, refer to the section on the performance ratings.

2. When the detection area becomes

When the difference between the ambient temperature and body temperature is large (more than 20°C 68°F), detection may occur in isolated areas outside the specified detection range.

3. Other handling cautions

- 1) Be careful not to allow dust or dirt to accumulate on the lens as this will adversely affect the detection sensitivity. 2) The lens is made of a soft material
- (polyethylene).

Avoid applying a load or impact since this will deform or scratch the lens, making proper operation impossible and causing a deterioration in its performance.

- 3) The sensor may be damaged if it is exposed to static with a voltage exceeding ±200V. Therefore, do not touch its terminals directly, and exercise adequate care in the handling of the sensor.
- 4) When the leads are to be soldered, solder them by hand for less than 3 seconds at a temperature of less than 350°C 662°F at the tip of the soldering iron. Avoid using a solder bath since this will causing a deterioration in the sensor's performance.

- 5) Do not attempt to clean the sensor. Cleaning fluid may enter inside the lens area causing a deterioration in performance.
- 6) When using the sensors with cables, it is recommended that cables which are shielded and as short as possible be used in order to safeguard against the effects of noise.

For the general precautions, refer to the Notes for Motion Sensors on page 27.